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2.094 Finite Element Analysis of Solids and Fluids Spring 2008

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2.094 — Finite Element Analysis of Solids and Fluids	Fall '08
Lecture 16 - F.E. analysis of Navier-Stokes fluids	
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Incompressible flow with heat transfer

We recall heat transfer for a solid:

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Governing differential equations

 $(k\theta_{,i})_{,i} + q^B = 0 \qquad \text{in } V$

$$\theta\Big|_{S_{\theta}} \text{ is prescribed, } k \frac{\partial \theta}{\partial n}\Big|_{S_{q}} = q^{S}\Big|_{S_{q}}$$

$$(16.2)$$

$$S_{\theta} \cup S_q = S \qquad S_{\theta} \cap S_q = \emptyset \tag{16.3}$$

Principle of virtual temperatures

$$\int_{V} \overline{\theta}_{,i} k \theta_{,i} dV = \int_{V} \overline{\theta} q^{B} dV + \int_{S_{q}} \overline{\theta}^{S} q^{S} dS_{q}$$
(16.4)

for arbitrary continuous $\overline{\theta}(x_1,x_2,x_3)$ zero on \mathcal{S}_{θ}

For a fluid, we use the Eulerian formulation.



Reading: Sec. 7.1-7.4, Table 7.3

(16.1)

$$\rho c_p v \left. \theta \right|_x - \left\{ \rho c_p v \left. \theta \right|_x + \frac{\partial}{\partial x} (\rho c_p v \theta) dx \right\} + \text{ conduction } + \text{ etc}$$
(16.5)

In general 3D, we have an additional term for the left hand side of (16.1):

$$-\nabla \cdot (\rho c_p \boldsymbol{v} \theta) = -\rho c_p \nabla \cdot (\boldsymbol{v} \theta) = -\rho c_p (\boldsymbol{\nabla} \cdot \boldsymbol{\nabla}) \theta - \underbrace{\rho c_p (\boldsymbol{v} \cdot \boldsymbol{\nabla}) \theta}_{\text{term (A)}}$$
(16.6)

where $\boldsymbol{\nabla} \cdot \boldsymbol{v} = 0$ in the incompressible case.

$$\boldsymbol{\nabla} \cdot \boldsymbol{v} = v_{i,i} = \operatorname{div}(\boldsymbol{v}) = 0 \tag{16.7}$$

So (16.1) becomes

$$(k\theta_{,i})_{,i} + q^B = \rho c_p \theta_{,i} v_i \Rightarrow (k\theta_{,i})_{,i} + \left(q^B - \rho c_p \theta_{,i} v_i\right) = 0$$
(16.8)

Principle of virtual temperatures is now (use (16.4))

$$\int_{V} \overline{\theta}_{,i} k \theta_{,i} dV + \int_{V} \overline{\theta} \left(\rho c_{p} \theta_{,i} v_{i} \right) dV = \int_{V} \overline{\theta} q^{B} dV + \int_{S_{q}} \overline{\theta}^{S} q^{S} dS_{q}$$

$$\tag{16.9}$$

Navier-Stokes equations

• Differential form

$$\tau_{ij,j} + f_i^B = \rho v_{i,j} v_j \tag{16.10}$$

with $\rho v_{i,j} v_j$ like term (A) in (16.6) = $\rho(\boldsymbol{v} \cdot \nabla) \boldsymbol{v}$ in V.

$$\tau_{ij} = -p\delta_{ij} + 2\mu e_{ij} \qquad e_{ij} = \frac{1}{2} \left(\frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right)$$
(16.11)

• Boundary conditions (need be modified for various flow conditions)

$$\tau_{ij}n_j = f_i^{S_f} \text{ on } S_f \tag{16.12}$$

Mostly used as $f_n = \tau_{nn} = \text{prescribed}$, $f_t = \text{unknown}$ with possibly $\frac{\partial v_n}{\partial n} = \frac{\partial v_t}{\partial n} = 0$ (outflow or inflow conditions).



And v_i prescribed on S_v , and $\mathbf{S}_v \cup \mathbf{S}_f = \mathbf{S}$ and $\mathbf{S}_v \cap \mathbf{S}_f = \emptyset$.

• Variational form

$$\int_{V} \overline{v}_{i} \rho v_{i,j} v_{j} dV + \int_{V} \overline{e}_{ij} \tau_{ij} dV = \int_{V} \overline{v}_{i} f_{i}^{B} dV + \int_{S_{f}} \overline{v}_{i}^{S_{f}} f_{i}^{S_{f}} dS_{f}$$
(16.13)

$$\int_{V} \bar{p} \nabla \cdot \boldsymbol{v} dV = 0 \tag{16.14}$$

 \bullet F.E. solution

We interpolate $(x_1, x_2, x_3), v_i, \overline{v}_i, \theta, \overline{\theta}, p, \overline{p}$. Good elements are



Both satisfy the inf-sup condition.

So in general,



Example:



For S_f e.g.

$$\tau_{nn} = 0, \qquad \frac{\partial v_t}{\partial n} = 0; \tag{16.15}$$

and $\frac{\partial v_n}{\partial t}$ is solved for. Actually, we frequently just set p = 0.

Frequently used is the 4-node element with constant pressure



It does not strictly satisfy the inf-sup condition. Or use

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3-node element with a bubble node. Satisfies inf-sup condition

1D case of heat transfer with fluid flow, v = constant

• Differential equations

$$k\theta'' = \rho c_p \theta' v \tag{16.17}$$

$$\theta|_{x=0} = \theta_L \qquad \theta|_{x=L} = \theta_R \tag{16.18}$$

In non-dimensional form

$$\frac{1}{\text{Pe}}\theta'' = \theta' \qquad (\text{now } \theta'' \text{ and } \theta' \text{ are non-dimensional})$$

$$\Rightarrow \frac{\theta - \theta_L}{\theta_R - \theta_L} = \frac{\exp\left(\frac{\mathrm{Pe}}{L}x\right) - 1}{\exp\left(\mathrm{Pe}\right) - 1} \tag{16.20}$$

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Reading: Sec. 7.4

Reading: Sec. 7.4.3

Reading:

p. 683

(16.19)



• F.E. discretization

$$\theta'' = \mathrm{Pe}\theta'$$

(16.21)

$$\int_0^1 \overline{\theta}' \theta' dx + \operatorname{Pe} \int_0^1 \overline{\theta} \theta' dx = 0 + \{ \text{ effect of boundary conditions } = 0 \text{ here} \}$$
(16.22)

Using 2-node elements gives



$$\frac{1}{(h^*)^2} \left(\theta_{i+1} - 2\theta_i + \theta_{i-1}\right) = \frac{\text{Pe}}{2h^*} \left(\theta_{i+1} - \theta_{i-1}\right)$$
(16.23)

$$Pe = \frac{vL}{\alpha} \tag{16.24}$$

Define

$$\operatorname{Pe}^{e} = \operatorname{Pe} \cdot \frac{h}{L} = \frac{vh}{\alpha} \tag{16.25}$$

$$\left(-1 - \frac{\operatorname{Pe}^{e}}{2}\right)\theta_{i-1} + 2\theta_i + \left(\frac{\operatorname{Pe}^{e}}{2} - 1\right)\theta_{i+1} = 0$$
(16.26)

what is happening when Pe^e is large? Assume two 2-node elements only.

$$\theta_{i-1} = 0 \tag{16.27}$$

$$\theta_{i+1} = 1 \tag{16.28}$$

$$\theta_i = \frac{1}{2} \left(1 - \frac{\operatorname{Pe}^e}{2} \right) \tag{16.29}$$



(16.30)

For $\operatorname{Pe}^{e} > 2$, we have *negative* θ_i (unreasonable).